

Freescale SemiconductorApplication Note

Qorivva MPC57xx e200zx Core Differences c55 process migration

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1 Introduction

MPC57xx devices are the latest generation of Automotive microcontrollers (MCU) based on the Power ArchitectureTM core. This generation is manufactured in a 55 nm wafer processing flow (c55). Previous generations of devices were manufactured in larger geometry technologies.

In addition to being manufactured in a smaller technology, the e200zx cores used in the c55 devices have been updated for higher speeds, lower power, and better die size utilization (equating to lower cost for the core itself). Many features of the cores are selectable by the definition requirements of the individual devices that use these cores. This document outlines major differences in the e200zx cores based on the options selected for devices in the MPC57xx family. While it lists the differences and gives a basic summary of the feature, this document does not fully explain the feature in detail. The core reference manuals should be consulted for additional information.

The table below shows the different technologies, as well as the different types of cores that are used by the different families of devices, starting with the first fully integrated Power Architecture core with embedded nonvolatile flash memory and peripherals (MPC555). There was an earlier Automotive Power Architecture, the MPC505/MPC509, however, it did not have integrated flash or peripherals.

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muroduction

Table 1. Automotive Power Architecture MCU technologies

Family	Manufacturing technology	Transistor geometry	Cores used
MPC555	CDR1	350 nm ¹	RCPU (Automotive RISC)
MPC56x Family	CDR3	250 nm ²	
Qorivva MPC55xx Family	HiP7	120 nm	e200z0, e200z1, e200z3, e200z6
Qorivva MPC56xx Family	c90	90 nm	e200z0, e200z3, e200z4, e200z6, e200z7
Qorivva MPC57xx Family	c55	55 nm	e200z0, e200z2, e200z4, e200z7

- 1. 0.35 micron
- 2. 0.25 micron

1.1 MPC57xx core instantiations

Many of the different devices in the MPC57xx family have a varying number of cores, including devices with different types of cores. The following table shows the cores that are instantiated on the different devices in the family. In addition, it shows the core that debuggers can access after reset with a blank flash (or when a valid reset configuration is not programmed into the flash). The table also shows whether any of the cores has the option of enabling a lock-step core. On this generation of MCUs, the lock-step core cannot be used as an independent core, it can only be enabled as a lock-step core. The lock-step core can be disabled to save power, however, this is not a significant amount of power.

Table 2. MPC57xx core summary

Device	Revision	Core 0	Core 1	Core 2	Lock-Step core ¹
MPC5726L	1 ²	e200z215An3	_	_	_
MPC5744K	1 ³	e200z420n3	_	e200z225n3 ⁴	Core 0 (e200z419)
MPC5744K	2 ²	e200z410Dn3	_	e200z225Bn3 ⁴	Core 0 (e200z409)
MPC5744P	1 ³	e200z4201n3	_	_	Core 0 (e200z419)
MPC5744P	2	e200z4251n3	_	_	Core 0 (e200z424)
MPC5746M	1.0/1.1 ³	e200z420n3	e200z420n3	e200z425n3 ⁴	Core 0 (e200z419)
MPC5746M	2	e200z410n3	e200z410n3	e200z425Bn3 ⁴	Core 0 (e200z409)
Future device 1	1 ³	e200z425n3	e200z425n3 ⁴	_	Core 0 (e200z424)
Future device 1	2	e200z425n3	e200z425n3 ⁴	_	Core 0 (e200z424)
MPC5748G	1	e200z4204n3 ⁴	e200z4204n3	e200z210n3	_
MPC5775K	1/1.1 ³	e200z4201n3	e200z7260n3	e200z7260n3	Core 0 (e200z419)
MPC5775K	2	e200z4201n3	e200z7260n3	e200z7260n3	Core 0 (e200z419)
Future device 2	1	e200z759n3 ⁴	e200z759n3	_	Core 1 (e200z758)
MPC5777M	13	e200z720n3	e200z720n3	e200z425Bn3 ⁴	Core 0 (e200z719)
MPC5777M	2	e200z710n3	e200z710n3	e200z425Bn3 ⁴	Core 0 (e200z709)

- 1. This column shows which core the lock-step core is associated with.
- 2. This device will not be supported by Freescale.
- 3. This revision is not intended for production.



4. Initial default boot core that executes code from the Boot Assist Flash (BAF). Debuggers have access to this core initially as well.

2 Differences between MPC57xx e200zx cores

The second major generation of the e200zx cores has minor variations for different devices. The following sections show all of the devices in the MPC57xx family and the variations of the cores used in each device (and version). The core options have been divided into three sections:

- Core instruction set and execution options (signal processing instruction options, saturated math instructions, floating point type options, instruction issue option, lock-step option etc.).
- Core bus interface options (memory protection options, end-to-end error correction code options, crossbar bus width, local memory options, and cache options)
- Core debug options (Nexus class, timestamp option, trace port width, and whether it has the fixed JTAG Nexus register access sequence)

The tables in the following sections are arranged by core complexity. The e200z210 is the "simplest" core (feature-wise) and with the e200z759 being the most complex.

2.1 e200zx core execution options

The first set of options that are available to be integrated into the cores instantiated into a particular MCU directly affect the cores, including what instructions are supported and how the instructions execute. These options are shown in the following table, then each of the options is explained in more detail.

General Purpose Registers Signal Processing Floating Point Instantiation Core Name Dual Issue Saturation Lockstep Revision Book e200z210 based cores MPC5748G 1.0 Core 2 e200z210n3 No Single No 32x32 No No No e200z215 based cores MPC5726L 1.0 Core 0 e200z215An3 Scalar Single No 32x32 No No e200z225 based cores MPC5744K 1.0 Core 2 e200z225n3 No 32x32 LSP Scalar Single No MPC5744K 2.0 Core 2 e200z225Bn3 No Single No 32x32 LSP Yes Scalar e200z410 based cores MPC5746M 2.0 Core 0/1 e200z410n3 No Single Delaved 32x32 No Yes Scalar MPC5744K 2.0 Core 0 e200z410Dn3 No Single Delayed 32x32 No Yes Scalar

Table 3. e200zx cores instruction differences

Table continues on the next page...



ווועerences between MPC57xx e200zx cores

Table 3. e200zx cores instruction differences (continued)

Device	Revision	Instantiation	Core Name	Book E	Dual Issue	Lockstep	General Purpose Registers	Signal Processing	Saturation	Floating Point	
			e200	z420 bas	ed cores				-		
MPC5744K	1.0	Core 0	e200z420n3	No	Dual	Delay ver.	32x32	No	No	Scalar	
MPC5746M MPC5744P	1.0/1.1	Core 0/1	e200z4201n3	No	Dual	Delay ver.	32x32	No	No	Scalar	
MPC5775K	1.0/1.1/	Core 0	e200z4201n3	No	Dual	Delay ver.	32x32	No	No	Scalar	
MPC5748G	1.0	Core 0 /1	e200z4204n3	No	Dual	No	32x32	No	No	Scalar	
e200z425 based cores											
MPC5746M	1.0	Core 2 ¹	e200z425n3	No	Dual	No	32x32	LSP	No	Scalar	
Future device 1	1.0	Core 0/1	e200z425n3	No	Dual	Delayed	32x32	LSP	No	Scalar	
Future device 1	2.0	Core 0/1 ¹	e200z425n3	No	Dual	Delayed	32x32	LSP	Yes	Scalar	
MPC5777M	1.0	Core 2 ¹	e200z425Bn3	No	Dual	No	32x32	LSP	No	Scalar	
MPC5746M	2.0	Core 2 ¹	e200z425Bn3	No	Dual	No	32x32	LSP	Yes	Scalar	
MPC5777M	2.0										
MPC5744P	2.0	Core 0	e200z4251n3	No	Dual	Delayed	32x32	LSP	No	Scalar	
			e200	z710 bas	ed cores						
MPC5777M	2.0	Core 0/1	e200z710n3	No	Single	Delayed	32x32	No	Yes	Scalar	
	•		e200	z720 bas	ed cores						
MPC5777M	1.0	Core 0/1	e200z720n3	No	Dual	Delayed	32x32	No	No	Scalar	
			e200	z7260 bas	sed cores						
MPC5775K	1.0/1.1/ 2.0	Core 1/2	e200z7260n3	No	Dual	No	32x64	SPE2	No	Vector	
e200z759 based cores											
Future device 2	1.0	Core 0/1 ¹	e200z759n3	Yes	Dual	Delayed	32x64	SPE1.1	No	Vector	

1. Initial boot core.

Book E Support - Previous e200z3 through e200z7 cores supported both the Power Architecture Book E instruction set and a more size efficient Variable Length Encoded (VLE) instruction set. The previous e200z0 cores used on some of the MPC5500 and MPC5600 devices supported only the VLE instruction set. Most of new MPC57xx devices support only the VLE instruction set, however, there is at least one device planned in the future that will support the full Book E instruction set.



Dual Issue - Some versions of the cores can issue two instructions and execute two instructions at a time. Other versions of the core will only execute a single instruction at a time. There are limitations of the instructions that can execute concurrently. Each core in an MCU could be defined as either dual- or single-issue variation for a particular MCU.

Lock-step Type - For safety applications, two cores execute instructions in parallel and compare the results to identify errors in the processor core. To reduce current requirements of the two cores running in parallel, one of the cores can be delayed by one clock. This spreads the peak current requirements of the core. Not all cores support the lock-step option. In the previous MPC56xx Family, the cores implemented a true lock-step where the two lock-step cores execute completely in parallel, with no delay.

General Purpose Registers - Although all of the e200zx cores are 32-bit Power Architecture cores, some versions of the cores support 64-bit registers that can be used by the Signal Processing Engine (SPE) Auxiliary Processing Unit (APU). Not all devices support the SPE APU.

Signal Processing Instruction support - There are several options for signal processing extensions to the core, either the Lightweight Signal Processing Unit or the Signal Processing Extension. These are shown in the following table. Some cores do not support any signal processing instructions.

Signal Processing Instructions	Version	Description
Lightweight Signal Processing Unit (LSP)	1	The Lightweight Signal Processing Unit (LSP) supports a limited number of basic math instructions to speed digital signal processing algorithms.
Signal Processing Extension	1.1	The Signal Processing Engine (SPE) Auxiliary Processing Unit
(SPE)	2	supports a full range of instructions for digital signal processing algorithms. There are currently two major versions of the SPE (1.1 and 2.1) that are supported on the MPC57xx devices.
No signal processing instructions	_	Some core variations do not include any type of signal processing extensions.

Table 4. Signal Processing instruction options

Saturation Instruction Support - To better support AutoSAR math functions, saturated math instructions are supported on some variations/versions of the cores. This allows optimization of some AutoSAR system calls to a single instruction.

Floating Point - Basic floating point instructions are supported on some variations of the cores. These can be defined as part of the base Power Architecture core. Either scalar or vector floating point options are supported. Vector mode is implemented in the SPE APU.

2.2 e200zx bus interface and memory options

The cores interface to the rest of the system through a bus interface. The majority of the e200zx cores support a dual bus structure (Harvard architecture) with a separate instruction fetch bus and a load/store bus.

The following table shows the differences between the e200z cores in regards to the cache sizes, local memory sizes, and bus interface and control.

Device Instantiation Instantiation DTCM XBAR Bus XBAR Bus D-cache I-cache

Table 5. e200zx cores bus interface and memory options

Table continues on the next page...

Qorivva MPC57xx e200zx Core Differences, Rev 0, 10/2013



ווועerences between MPC57xx e200zx cores

Table 5. e200zx cores bus interface and memory options (continued)

			1		1		 	1		
Device	Revision	Instantiation	Core Name	MPU	e2eECC	XBAR Bus	DTCM	ITCM	D-cache	l-cache
MPC5748G	1.0	Core 0	e200z210n3	No	Yes	64I/64D	No	No	No	No
		1	e200)z215 bas	ed cores		l			
MPC5726L	1.0	Core 0	e200z215An3	No	No	32I/32D	No	No	No	No
		!	e200)z225 bas	ed cores	!		!		!
MPC5744K	1.0	Core 2	e200z225n3	8	Yes	64I/64D	48K	16K	No	No
MPC5744K	2.0	Core 2	e200z225Bn3	8	Yes	64I/32D	48K	16K	No	No
		1	e200	0z420 bas	ed cores	!		!		!
MPC5746M	2.0	Core 0/1	e200z410n3	24	Yes	64I/64D	64K	16K	4K	8K
MPC5744K	2.0	Core 0	e200z410Dn 3	24	Yes	64I/64D	64K	16K	2K	4K
			e200	0z420 bas	ed cores					
MPC5744K	1.0/1.1	Core 0	e200z420n3	24	Yes	64I/64D	64K	16K	4K	8K
MPC5746M		Core 0/1								
MPC5744P	1.0	Core 0	e200z4201n3	24	Yes	64I/64D	64K	No	4K	8K
MPC5775K	1.0/1.1/ 2.0	Core 2	e200z4201n3	24	Yes	64I/64D	64K	No	4K	8K
MPC5748G	1.0	Core 1/2	e200z4204n3	No	Yes	64I/64D	No	No	4K	8K
		1	e200)z425 bas	ed cores	•		•		•
MPC5746M	1.0	Core 2	e200z425n3	24	Yes	64I/64D	32K	16K	No	8K
Future device 1	1.0	Core 0/1	e200z425n3	24	Yes	64I/64D	32K	16K	No	8K
Future device 1	2.0	Core 0/1	e200z425n3	24	Yes	64I/64D	32K	16K	No	8K
MPC5777M	1.0	Core 2	e200z425Bn3	24	Yes	64I/32D	64K	16K	No	8K
MPC5746M	2.0	Core 2	e200z425Bn3	24	Yes	64I/32D	64K	16K	No	8K
MPC5777M	2.0	-								
MPC5744P	2.0	Core 0	e200z4251n3	24	Yes	64I/64D	64K	No	4K	8K
			e200	0z710 bas	ed cores					
MPC5777M	2.0	Core 0/1	e200z710n3	24	Yes	64I/64D	64K	16K	4K	16K
			e200	0z720 bas	ed cores	•		•		•
MPC5777M	1.0	Core 0/1	e200z720n3	24	Yes	64I/64D	64K	16K	4K	16K
			e200	z7260 bas	sed cores					
MPC5775K	1.0/1.1/ 2.0	Core 1/2	e200z7260n3	24	Yes	64I/64D	64K	No	16K	16K
	e200z759 based cores									
Future device 2	1.0	Core 0/1	e200z759n3	MMU	No	64I/64D	No	No	16K	16K

Memory Protection Unit (MPU) - The Memory Protection Unit (MPU) allows memory regions to be protected from being accessed by certain cores, protected from being modified by certain cores, protected from core execution, for enabling or disabling of being cached, and for other safety protection features.



Differences between MPC57xx e200zx cores

Memory Management Unit (MMU) - The Memory Management Unit is similar to the Memory Protection unit in that it allows memory regions to be protected from being accessed by certain cores, protected from being modified, and for enabling/disabling of the cache for that memory region. However, it also supports the capability of remapping a logical (or virtual) memory address into a physical hardware memory address, including the capability to map addresses based on a Process ID. The MMU is much more complicated than the MPU, this is only a brief summary of the MMU capabilities. For more information about the MMU, see a core reference manual or device reference manual that supports the MMU.

End-to-End Error Correction Coding (e2eECC) - End-to-end (e2e) Error Correction Coding (ECC) provides an additional layer of safety by including ECC on all bus transactions. The ECC for the transfer is generated on the transmitting end of the transaction and checked at the receiving end. e2eECC is an optional feature that can be implemented with the core and system interfaces.

Cross-Bar (XBAR) interface - In general, the e200zx cores have traditionally implemented a 64-bit bus interface to the Cross-Bar switch. On the newer e200zx cores, the instruction bus interface remains 64-bit, however, the data load/store bus on some versions of the cores are implemented with a 32-bit interface to save power and die area (cost).

Local Data Memory (DTCM) - Some cores support a fast local data memory (SRAM). This is sometimes referred to as a tightly coupled memory (DTCM). The size of this SRAM is definable for a given core variant. Not all devices implement local memory. The local data memory allows for fast access of variables that are required frequently by a single core.

Local Instruction Memory (ITCM) - Some cores support a fast local instruction memory (SRAM). This is sometimes referred to as a tightly coupled memory (ITCM). The size of this SRAM is definable for a given core variant. Not all devices implement local memory. The local instruction memory can be loaded with frequently executed software routines, this is similar to the concept of locking some regions of cache for frequently used subroutines or functions.

Data Cache (**D-Cache**) - Data cache allows fast access to recently used data from the load/store bus from memory space outside of the core complex, typically the device internal flash or external 1 (to the device) memory. Different sizes of D-Cache can be instantiated (as defined for a device) in a particular core.

Instruction Cache (I-Cache) - Instruction cache allows fast access to recently loaded instructions from memory (typically flash). Different sizes of I-Cache can be instantiated (as defined for a device) in a particular core.

2.3 e200zx debug options

As with other features of the core, the debug options can be determined by the definition of the device requirements. These allow different kinds of support depending on the requirements of the overall system. These options are shown in the following table. Each of the options is then explained.

Pevice

Instantiation

Core Name

Core Name

Timestamp

Timestamp

ATAG Nexus State

Machine Reset

DQM DQTAG packet type

Table 6. e200zx cores debug feature options

Table continues on the next page...

^{1.} Not all devices support an external bus.



יווים erences between MPC57xx e200zx cores

Table 6. e200zx cores debug feature options (continued)

			res debug it	-	· `		-		
Device	Revision	Instantiation	Core Name	Nexus class support	Timestamp	Nexus Port Width (MDO)	JTAG Nexus State	Machine Reset	DQM DQTAG packet type
MPC5748G	1.0	Core 2	e200z210n3	3+	Yes (unbuffere d)	16 or 12	Fix	ed	Fixed
			e200z215 bas	ed cores					
MPC5726L	1.0	Core 0	e200z215An3	3+	No	30	Fix	ed	Fixed
	1	1	e200z225 bas	ed cores					
MPC5744K	1.0	Core 2	e200z225n3	3+	No	30	Fix	ed	Fixed
MPC5744K	2.0	Core 2	e200z225Bn3	3+	Yes (unbuffere d)	30	Fix	ed	Fixed
e200z410 based cores									
MPC5746M	2.0	Core 0/1	e200z410n3	3+	Yes (unbuffere d)	30	Fix	ed	Fixed
MPC5744K	2.0	Core 0	e200z410Dn3	3+	Yes (unbuffere d)	30	Fix	ed	Fixed
	1	1	e200z420 bas	ed cores					1
MPC5744K	1.0	Core 0	e200z420n3	3+	No	30	_	_	Variable
MPC5746M	1.0/1.1	Core 0/1							
MPC5744P	1.0	Core 0	e200z4201n3	3+	No	30 or 4	Fix	ed	Fixed
MPC5775K	1.0/1.1/ 2.0	Core 0	e200z4201n3	3+	Yes (buffered)	30 or 16	Fix	ed	Fixed
MPC5748G	1.0	Core 1/2	e200z4204n3	3+	Yes (buffered)	16 or 12	Fix	ed	Fixed
			e200z425 bas	ed cores					
MPC5746M	1.0	Core 2	e200z425n3	3+	No	30	_	_	Variable
Future device 1	1.0	Core 0/1	e200z425n3	3+	No	30 or 4 ¹	Fix	ed	Fixed
Future device 1	2.0	Core 0/1	e200z425n3	3+	No	30 or 4 ¹	Fix		Fixed
MPC5777M	1.0	Core 2	e200z425Bn3	3+	No	30	Fix		Fixed
MPC5746M MPC5777M	2.0	Core 2	e200z425Bn3	3+	Yes (unbuffere d)	30	Fix	ed	Fixed
MPC5744P	2.0	Core 0	e200z4251n3	3+	No	30 or 4	Fix	ed	Fixed
207 1 11		1 22.00	e200z710 bas			00 01 1			
MPC5777M	2.0	Core 0/1	e200z710n3	3+	No ²	30	Fix	ed	Fixed
	1				L				

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Table 6.	e200zx cores	debug	feature o	ptions	(continued))
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Device	Revision	Instantiation	Core Name	Nexus class support	Timestamp	Nexus Port Width (MDO)	JTAG Nexus State	Machine Reset	DQM DQTAG packet type
			e200z720 bas	ed cores					
MPC5777M	1.0	Core 0/1	e200z720n3	3+	No	30	Fix	ed	Fixed
	ı		e200z7260 bas	sed cores					
MPC5775K	1.0/1.1/ 2.0	Core 1/2	e200z7260n3	3+	Yes (buffered)	30 or 16 ³	Fix	ed	Fixed
e200z759 based cores									
Future device 2	1.0	Core 0/1	e200z759n3	3+	No	16 or 12	Fix	ed	Variable

- Although a 4-bit parallel Nexus MDO port is implemented in the core, it is not possible to select this mode in the Nexus Aurora Router (NAR).
- 2. Unbuffered timestamps had been planned for these cores.
- 3. Although a 16-bit parallel Nexus MDO port can be selected, pins are not available on the package to allow it to be accessed.

Nexus Class support - The IEEE-ISTO 5001 standard supports multiple "Classes" of support. The e200zx cores can be instantiated with different levels of support. An overview of the Nexus Class definitions can be found in AN4088 "MPC5500/MPC5600 Nexus Support Overview".

Nexus Timestamp Support - The IEEE-ISTO 5001 standard allows Nexus messages to have timestamps appended to the message to better track the exact timing of the messages. Timestamps are an optional feature. When implemented on the e200zx cores, the timestamps can either be implemented as buffered or non-buffered. In general, the unbuffered mode is implemented on devices with a Nexus Aurora Router (NAR) as the Nexus output controller. Devices that instantiate the Nexus Port Controller (NPC) use the buffered timestamps. This difference is due to the minimal time that messages spend in the core Nexus buffers on NAR devices since the NAR implements dedicated input queues from each Nexus client on the device. However, the NPC only acts as a switch from the output of the individual Nexus clients directly to the Nexus output port. The NPC implements no buffers for holding messages. On NPC based devices, each client implements the buffers that hold Nexus messages while other Nexus clients are transmitting their message out of the device.

Table 7. Nexus Timestamp support

Timestamp type	Description			
Buffered	The buffered option appends the timestamp to the Nexus message when the message is written into the e200zx core Nexus message buffers.			
Unbuffered	The unbuffered option appends the timestamp to the Nexus message when the message leaves the core buffers and is transferred to the device level NPC or NAR.			

Nexus Port Width - The width of the Nexus Auxiliary port (trace information) is definable for the e200zx core definition. Typically, a 30-bit Message Data Output port is used when supporting the IEEE-ISTO 5001-2012 high-speed serial Nexus Aurora port. Smaller sizes are generally used for a parallel Message Data Output Nexus port. Some core variations support two port widths, while some variations support only a single port width. This is primarily to support either the Nexus Port



Controller (NPC, used on the previous MPC5500/MPC5600 devices) that supports selection between two different port widths, and the Nexus Aurora Router (NAR, used on some of the MPC5700 devices) that supports only a single port width. The port width, along with the port speed, define the maximum bandwidth that is available for trace information.

Table 8. Typical Nexus port width usage

Number of Message Data Outputs	Typical use
4	Low-bandwidth parallel Nexus Auxiliary trace port
8	Medium-bandwidth parallel Nexus Auxiliary trace port ¹
12	Medium-bandwidth parallel Nexus Auxiliary trace port
16	High-bandwidth parallel Nexus Auxiliary trace port
30	Very high-bandwidth serial Nexus Aurora trace

1. This depends on the number of cores and the Nexus parallel port clock speed.

JTAG Nexus State Machine Reset - In some cases, the Nexus state machine in the e200zx core does not get properly reset when the JTAG TAP is changed to a different JTAG client (to a different core or other client). Previously, the Nexus JTAG state machine was reset only if the JTAG IR changed the CMD/DATA. It has been modified to reset the Nexus state machine anytime the JTAG state machine goes through the UPDATE_IR state.

Data Acquisition Message (DQM) Data Tag (DQTAG) packet type - The Data Tag (DQTAG) packet of the Data Acquisition Message (DQM) is defined by the IEEE-ISTO 5001 standard as a Fixed length field. Some versions of the cores incorrectly implement the DQTAG as a Variable length packet instead of the Fixed length field.

Appendix A Revision history

The table below shows the complete revision history of this document.

Table A-1. Revision History

Revision	Author	Changes
0	Randy Dees	Initial customer release.





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